

Automatic Forecasting Support System for Business Analytics applications based on Unobserved Components models

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Outline

- 1 Introduction
- 2 Unobserved Components models
- 3 Forecasting methods
- 4 Case study
- 5 Conclusions

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- Disseminate **SSpace**, a MATLAB toolbox implementing most methods used in this work (Villegas and Pedregal, 2018; <https://bitbucket.org/predilab/sspace-matlab>).

Exponential Smoothing continues to be the most used modeling technique in business and industry, at least in areas ranging from inventory management and scheduling to planning. Several reasons:

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ARIMA is the second method most used, because it is well-known to many researchers and also there are many packages implementing even automatic identification procedures.

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- Software is scarcer.

Unobserved Components models

UC models aim at decomposing a vector of time series into meaningful components explicitly, namely trend, cycle, seasonal, and irregular. Other components may be considered as well, typically cycles and components relating the output variables to inputs modeled as linear regressions, transfer functions or non-linear relationships. A general representation is given by

$$z_t = T_t + C_t + S_t + f(u_t) + I_t \quad (1)$$

where z_t is a vector of time series, T_t , C_t , S_t and I_t stand for vectors of trends, cycles, seasonal and irregular components, respectively. The term $f(u_t)$ models the relation between a vector of inputs u_t and the outputs z_t .

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The UC model is set up in a State Space framework and the Kalman Filter and Smoothing algorithms provide the optimal estimates of the state vector and its covariance matrices. Maximum Likelihood estimation may be done on the general formulation of SS systems, etc.

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 - **TRAMO**: Gómez and Maravall (2001) implemented in TRAMO with and without outliers identification.

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 - **R-ETS**: implemented in the R package 'forecast' (Hyndman and Khandakar, 2008).
- Combination methods: i) **Mean** and ii) **Median** of AR, ARIMA, UC and ETS methods estimated with **SSpace**.

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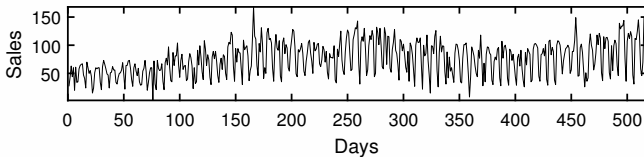
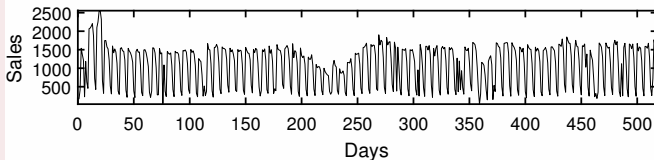
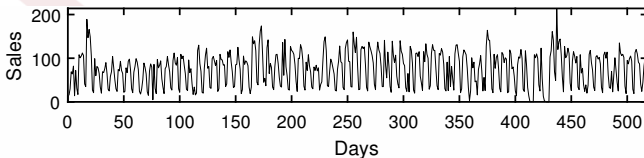
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 - Irregular: White noise or AR coloured noise orders up to 3rd order.

Data

The proposed evaluation of the models was carried out on the 166 products sales from a food franchise in Spain. The company specializes in selling everyday dishes made from natural products at affordable prices in take-away and take-in formats. 517 daily sales observations were made available for each product with 414 observations used for in-sample estimation and the remainder for out-of-sample evaluation. A set of 90, 14 days ahead forecast rounds was carried out for each product.

Data



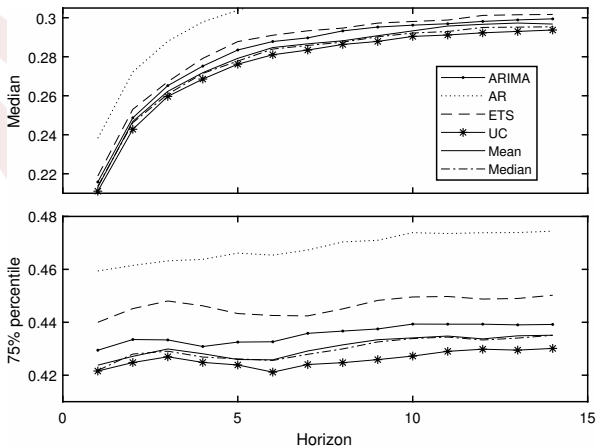
Metrics

Cumulative Absolute Scaled Error:

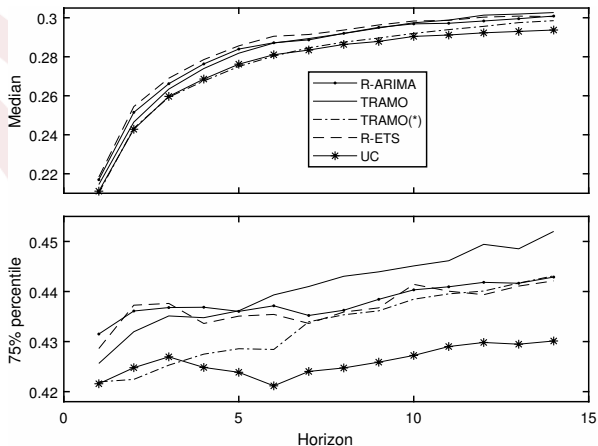
$$CsE_h = \frac{1}{h} \sum_{l=1}^h sE_h$$

where the Absolute Scaled Error is

$$sE_h = \frac{|z_{T+h} - \hat{z}_{T+h}|}{\frac{1}{T} \sum_{i=1}^T z_i}$$



Median (top panel) and 75 % percentile (bottom panel) of CsE_h for all models implemented in **SSpace**.



Median (top panel) and 75 % percentile (bottom panel) of CsE_h for alternative models.

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- The median of CsE_h and sE_h shows that most models offer very similar results. However, as the bottom panel shows, differences are more apparent when the 75 % percentile is considered. The advantage of UC models is clearer in these cases.

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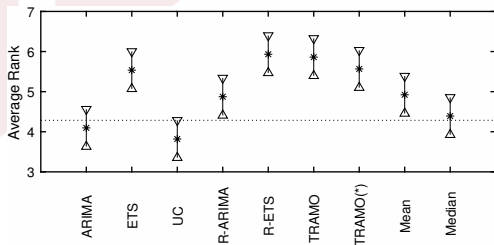
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- Results shown for **R-ARIMA** are obtained constraining the seasonal differences to 1 in the automatic procedure. The errors are considerably larger when this parameter is selected fully automatically with formal unit roots.

- **TRAMO** and **TRAMO(*)** are worse than **R-ARIMA** and **R-ETS** for longer horizons, although better for shorter ones.

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Formal statistical tests to evaluate whether differences are statistically significant. This can be done with rank tests (Koning *al.*, 2005) that rank methods by forecast error measurement (Mean Absolute Error in this case)



Thank you for your attention!

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